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1 ELEMENTS OF LINEAR SYSTEM THEORY 1.1 INTRODUCTION This book deals with the analysis and design of linear control systems. A prerequisite for studying linear control systems is a knowledge of linear system theory. We therefore devote this first chapter to a review of the most important ingredients of linear system theory.

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techniques available in linear system theory, the tools for analysis and design of nonlinear systems are limited to some very special categories. First, there are the relatively simple techniques, such as phase-plane analysis, which are graphical in nature and thus of limited generality.

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This edition has been enhanced as a solid undergraduate and first-year graduate text; it emphasizes applying control theory fundamentals to both analog and sampled-data single-input single-output (SISO) feedback control systems. At the same time, the coverage of digital control systems is greatly expanded.

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Preface xxi. called the pole placement theorem, is one of the central achievements of modern control theory. The tenth chapter is devoted to observers: algorithms for deducing the system state from measured inputs and outputs. The design of observers is very similar to the stabilization and pole placement procedures.

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One also defines nonlinear and discrete-time systems with output in an analogous way, or more abstractly by adding an output map to the axiomatic definition of system via transitions (1.31). A linear feedback law that depends only on the allowed measurements is then, in terms of this notation, of the form  $u(t) = KCx(t)$ .

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